

Midterm: Eng. 0138 Advanced Control II

February 26, 2003.

8:30 AM to 9:30 AM

Closed Book exam.

Programmable calculators are not allowed.

Q-1 (8 marks)

Consider the following system

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, C = [1 \ 0]$$

a) Write the system in controllable canonical form, observable canonical form and diagonal canonical form or Jordan canonical form.

b) Compute e^{At} .

Q-2 (17 marks)

Consider the system defined by:

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

where,

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, C = [1 \ 0]$$

a) Check the state controllability and observability of the system.

b) Using the state feedback control $u = -Kx + lr$, determine K and l such that the closed loop system will have:

- Zero-steady-state error for a unit-step input
- 10% overshoot and 10 seconds settling time.

c) Give the block diagram of the observer-based state feedback controller.

$$\text{Percent overshoot: } \%OS = 100 \exp\left(\frac{-\xi\pi}{\sqrt{1-\xi^2}}\right)$$

$$\text{Settling time at 2\%: } T_s \approx \frac{4}{\xi\omega_n}$$

$$y = Cx \quad A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$C = [1, 0]$$

Step 1

Find transfer function.

$$\dot{X} = Ax + Bu \Rightarrow sX(s) = Ax + Bu$$

$$X(s)(sI - A) = Bu$$

$$X(s) = (sI - A)^{-1} Bu$$

$$Y = Cx$$

$$Y(s) = C(sI - A)^{-1} B \cdot U(s)$$

$$Y(s) = C(sI - A)^{-1} B$$

$$U(s)$$

$$T.F. = [1 \ 0] \left[\begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ -3 & -4 \end{pmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= (1 \ 0) \begin{pmatrix} s+4 & 1 \\ -3 & s \end{pmatrix} = \begin{pmatrix} s+4 & 1 \\ -3 & s \end{pmatrix}$$

$$= \frac{1}{(s+4)(s+1)} = \frac{X(s)}{U(s)}$$

$$Y'' + 4Y' + 3Y = U(s)$$

$$X_1 = Y$$

$$\dot{X}_1 = \dot{Y} = X_2$$

$$\dot{X}_2 = \ddot{Y}$$

$$\dot{X}_2 = -4X_2 - 3X_1 + U(s)$$

$$\dot{X}_1 = X_2$$

$$A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$C = [1 \ 0]$$

$$D = 0$$

Observer

$$A_{oc} = A^T C_c$$

$$B_{oc} = C_c^T$$

$$C_{oc} = B_c^T = [0 \ 1] \quad p=0$$

$$A_{oc} = \begin{bmatrix} 0 & -3 \\ 1 & -4 \end{bmatrix}$$

$$B_{oc} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$C^{u_{x1}} = \frac{-3}{(s+3)(s+1)}$$

$$Y(s) \quad s+3 \mid \frac{-3}{-2} = \frac{3}{2} = A$$

$$\frac{3}{2} \cdot \frac{1}{(s+3)} = \frac{3}{2} \frac{1}{(s+1)}$$

$$Y(s) \quad (s+1) \mid \frac{-3}{2} \Rightarrow \frac{-3}{2}$$

$$e^{u_{x2}} = \frac{s}{(s+3)(s+1)}$$

$$Y(s) \quad (s+3) \mid = \frac{s+3}{s+2} = A \quad \frac{A}{(s+3)} + \frac{B}{(s+1)} = s$$

$$\frac{3}{2} \cdot \frac{1}{(s+3)} - \frac{1}{2} \cdot \frac{1}{(s+1)}$$

$$Y(s) \quad (s+1) \mid \frac{-1}{2} = B$$

$$e^{at} = \begin{bmatrix} \left(\frac{1}{2} \cdot \frac{1}{(s+3)} + \frac{3}{2} \frac{1}{(s+1)} \right) & \left(\frac{1}{2(s+3)} - \frac{1}{2(s+1)} \right) \\ \left(\frac{3}{2(s+3)} - \frac{3}{2(s+1)} \right) & \left(\frac{3}{2(s+3)} - \frac{1}{2(s+1)} \right) \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{2} e^{-3t} + \frac{3}{2} e^{-t} \\ \frac{3}{2} e^{-3t} + \frac{3}{2} e^{-t} \end{bmatrix}$$

$$a) \quad C = \begin{bmatrix} B & AB & A^{n-1}B \end{bmatrix} = \begin{bmatrix} B & AB \end{bmatrix}$$

$$AB = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\text{Det} \Rightarrow \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}$$

$$0 \neq -1 \quad \checkmark$$

Obser

$$O = \begin{bmatrix} C \\ CA \\ CA^{n-1} \end{bmatrix} \Rightarrow$$

$$CA = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$\text{Det} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 1 \neq 0 \quad \checkmark$$

$$b) \quad \dot{x} = Ax + Bu \quad u = -Kx + lr$$

$$y = Cx$$

$$\dot{x} = Ax - BKx + Blr$$

$$\dot{x} = x(A - BK) + Blr$$

$$x(SI - (A - BK)) = Blr$$

$$x = (SI - (A - BK))^{-1} Blr$$

$$y(t) = C [SI - (A - BK)]^{-1} Blr \quad ?$$

$$\lim_{s \rightarrow 0} y = \frac{1}{s} C [-(A - BK)^{-1}] Blr$$

$$1 = C [-(A - BK)^{-1}] Bl$$

$$2 = [C(A + BK)^{-1}B]^{-1}$$

find k?

$$TF = \frac{1}{(s+3)(s+1)}$$

$$u \frac{C_1}{(s+3)} + \frac{C_2}{(s+1)} = 1$$

$$* A = \begin{bmatrix} -3 & 0 \\ 0 & -1 \end{bmatrix}$$

$$(s+1) \Big| \frac{1}{s-1} = C_2 \quad C_1 \Big| \frac{s+3}{s-1} \Big| \frac{1}{-2}$$

$$C_1 = \frac{1}{2} \quad C_2 = -\frac{1}{2}$$

$$* C = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

$$B \neq X_1 = \frac{1}{s+3} u(t) \Rightarrow X(s) + 3X = \frac{1}{s+3} u(t)$$

$$* B = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$D = 0$$

$$(?) \text{ Jordan } \frac{1}{(s+3)(s+1)}$$

$$X(t) = e^{At} X(0) + \int_0^t e^{A(t-\tau)} B u d\tau$$

$$e^{At} = \mathcal{L}^{-1}((sI - A)^{-1})$$

$$e^{At} = \mathcal{L}^{-1} \left(\left[\begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix} \right]^{-1} \right) \Rightarrow \begin{bmatrix} s & -1 \\ +3 & s+4 \end{bmatrix}^{-1}$$

$$\det = s^2 + 4s + 3$$

$$e^{At} = \mathcal{L}^{-1} \begin{bmatrix} \frac{s+4}{(s+3)(s+1)} & \frac{1}{(s+3)(s+1)} \\ \frac{-3}{(s+3)(s+1)} & \frac{s}{(s+3)(s+1)} \end{bmatrix} = \begin{bmatrix} s+4 & 1 \\ -3 & s \end{bmatrix} \frac{1}{(s+3)(s+1)}$$

$$e^{At} \Rightarrow s+4 = \frac{A}{(s+3)} + \frac{B}{s+1} \quad (s+3) Y(s) \Big| \frac{1}{-2} = A$$

$$-\frac{1}{2} \left(\frac{1}{s+3} \right) + \frac{3}{2} \frac{1}{s+1}$$

$$(s+1) Y(s) \Big| \frac{3}{2} = B$$

$$e^{a_{11}} = \frac{-1}{2} \left(\frac{1}{s+3} \right) + \frac{3}{2} \left(\frac{1}{s+1} \right)$$

$$e^{a_{12}} = \frac{A}{s+3} + \frac{B}{s+1} = 1 \quad (s+3) Y(s) \Big| \frac{1}{-2} = B$$

$$e^{a_{22}} = \frac{1}{2} \left(\frac{1}{s+3} \right) + \frac{1}{2} \left(\frac{1}{s+1} \right) \quad (s+1) Y(s) \Big| \frac{1}{2} = A$$

$$\det \left[\begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \left[\begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} (k_1 \ k_2) \right] \right]$$

$$\Rightarrow \begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \left[\begin{pmatrix} 0 & 1 \\ 2 & 2 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ k_1 & k_2 \end{pmatrix} \right]$$

$$\Rightarrow \begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 1-k_1 & 2-k_2 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} s & -1 \\ -1+k_1 & s-2+k_2 \end{pmatrix} \Rightarrow$$

$$= (s^2 - 2s + s k_2) + (-1 + k_1)$$

$$= s^2 + s(-2 + k_2) + (-1 + k_1)$$

$$\%OS = 100 e^{\frac{-\pi \zeta}{\sqrt{1-\zeta^2}}} \Rightarrow \left(-\ln \frac{10}{100} \right)^2 = \frac{\pi^2 \zeta^2}{1-\zeta^2}$$

$$\Rightarrow \begin{aligned} X^2 - 3^2 \zeta^2 &= \pi^2 \zeta^2 \\ \frac{X^2}{\pi^2 + X^2} &= \zeta^2 \\ \zeta &= 0.591155033 \end{aligned}$$

$$10 = 4$$

$$0.59 \cdot \omega_n$$

$$\omega_n = 0.676341452$$

$$\omega_n = 0.457843654$$

$$s^2 + 0.8s + 0.457843654 = s^2 + s(-2 + k_2) + (-1 + k_1)$$

$$0.8 = -2 + k_2$$

$$k_2 = 2.8$$

$$-1 + k_1 = 0.4578$$

$$k_1 = 1.458$$

$$= \left[\begin{pmatrix} 1 & 0 \end{pmatrix} \left[\begin{pmatrix} 0 & -1 \\ -1 & -2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} (k_1 \ k_2) \right]^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]^{-1}$$

$$\Rightarrow \left[\begin{pmatrix} 0 & -1 \\ -1 & -2 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ k_1 & k_2 \end{pmatrix} \right]$$

$$\Rightarrow \begin{pmatrix} 0 & -1 \\ -1+k_1 & -2+k_2 \end{pmatrix}^{-1} \Rightarrow \begin{bmatrix} -2+k_2 & 1 \\ -(1+k_1) & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

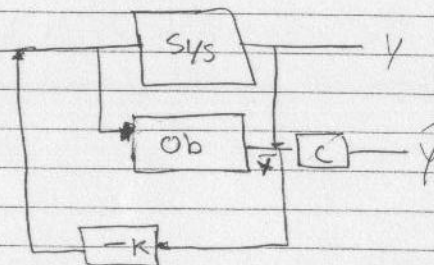
$$2 \times 2 \quad 2 \times 1$$

$$\Rightarrow \left[\begin{pmatrix} 1 & 0 \end{pmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix} \right]^{-1} \Rightarrow 1$$

$$1 \times 2 \quad 2 \times 2 \quad 2 \times 1$$

$$L = 1$$

c)



Q1
a)

Given:

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, C = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$y'' + 4y' + 3y = u(s)$$

$$\dot{x}_1 = \dot{y}_1 = x_2 \quad (y+3)(y+1)$$

$$\dot{x}_2 = \ddot{y}_1$$

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = -3x_1 - 4x_2 + u$$

$$\dot{x} = Ax + Bu \Rightarrow sX(s) = AX(s) + Bu \rightarrow sX(s) - AX(s) = Bu$$

$$X(s)(sI - A) = Bu$$

$$X(s) = (sI - A)^{-1} Bu$$

$$X(s)[s - A] = Bu$$

Diagonal

$$T.F. = \frac{1}{(s+3)(s+1)} = \frac{uC_1}{s+3} + \frac{uC_2}{s+1} = 1$$

$$y(t) = Cx$$

$$y(t) = C(sI - A)^{-1} Bu(t)$$

$$\frac{y(t)}{u(t)} = C(sI - A)^{-1} B$$

$$= \begin{bmatrix} 1 & 0 \end{bmatrix} \left[\begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ -3 & -4 \end{pmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} s & -1 \\ 3 & s+4 \end{pmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{pmatrix} s+4 & -1 \\ -3 & s \end{pmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ s \end{bmatrix} = 1$$

Controllable

$$C_c = A = \begin{bmatrix} 0 & 1 \\ -3 & -4 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$D = 0$$

$$\begin{bmatrix} (s+4) & 1 \\ 1 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 1$$

$$\Rightarrow \frac{y(s)}{u(s)} = \frac{1}{(s+3)(s+1)} = \frac{1}{s^2 + 4s + 3}$$

Observ.

$$AO_c = A^T C_c = \begin{bmatrix} 0 & -3 \\ 1 & -4 \end{bmatrix}$$

$$BO_c = C_c^T$$

$$BO_c = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$CO_c = BC^T = \begin{bmatrix} 0 & 1 \end{bmatrix}$$

$$D = 0$$

$$A = \begin{bmatrix} -3 & 0 \\ 0 & -1 \end{bmatrix}$$

$$C_1 = s+1 \Big|_{s=-1} \frac{1}{(-1+3)} = \frac{1}{2} \quad C_2 = s+3 \Big|_{s=-3} \frac{1}{-3+1} = \frac{1}{2}$$

$$C_1 = \frac{1}{2}, C_2 = -\frac{1}{2}$$

$$C = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

$$B \Rightarrow x_1 = \frac{1}{s+3} u(t)$$

$$x(s) + 3x =$$

$$B = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$D = 0$$

$$\det = S(S+4)+3 \\ = S^2+4S+3 = (S+3)(S+1)$$

Q1 b)

$$e^{At} = \mathcal{L}^{-1}[(SI-A)^{-1}]$$

$$e^{At} = \mathcal{L}^{-1}\left[\left[\begin{array}{cc} S & 0 \\ 0 & S \end{array}\right] - \left[\begin{array}{cc} 0 & 1 \\ -3 & -1 \end{array}\right]\right]^{-1} = \mathcal{L}^{-1}\left[\begin{array}{cc} S & -1 \\ 3 & S+4 \end{array}\right]^{-1} = \mathcal{L}^{-1}\left[\begin{array}{cc} \frac{S+4}{(S+3)(S+1)} & \frac{-1}{(S+3)(S+1)} \\ \frac{3}{(S+3)(S+1)} & \frac{S}{(S+3)(S+1)} \end{array}\right]$$

(11)

$$\frac{S+4}{(S+3)(S+1)} = \frac{A}{S+3} + \frac{B}{S+1}$$

$$= \frac{1}{2}\left(\frac{1}{S+3}\right) + \frac{3}{2}\left(\frac{1}{S+1}\right)$$

$$\mathcal{L}^{-1} = \frac{1}{2}e^{-3t} + \frac{3}{2}e^{-t}$$

$$(S+3)Y(S) \Big|_{S=-3} \quad \frac{S+4}{S+1} = \frac{-3+4}{-3+1} = \frac{1}{-2} = A$$

$$(S+1)Y(S) \Big|_{S=-1} \quad \frac{S+4}{S+3} = \frac{-1+4}{-1+3} = \frac{3}{2} = B$$

(12)

$$\frac{1}{(S+3)(S+1)} = \frac{A}{S+3} + \frac{B}{S+1}$$

$$\mathcal{L}^{-1} = \frac{1}{2}e^{-3t} + \frac{1}{2}e^{-t}$$

$$S+3 \Big|_{S=-3} \quad \frac{1}{(S+1)} = \frac{1}{-2} = A$$

$$S+1 \Big|_{S=-1} \quad \frac{1}{(S+3)} = \frac{1}{2} = B$$

(21)

$$\frac{3}{(S+3)(S+1)} = \frac{A}{S+3} + \frac{B}{S+1}$$

$$\mathcal{L}^{-1} = \frac{-3}{2}e^{-3t} + \frac{3}{2}e^{-t}$$

$$S+3 \Big|_{S=-3} \quad \frac{3}{(S+1)} = \frac{3}{-2} = A$$

$$S+1 \Big|_{S=-1} \quad \frac{3}{(S+3)} = \frac{3}{2} = B$$

(22)

$$\frac{S}{(S+3)(S+1)} = \frac{A}{S+3} + \frac{B}{S+1}$$

$$\mathcal{L}^{-1} = \frac{3}{2}e^{-3t} - \frac{1}{2}e^{-t}$$

$$S+3 \Big|_{S=-3} \quad \frac{S}{(S+1)} = \frac{-3}{-2} = \frac{3}{2} = A$$

$$S+1 \Big|_{S=-1} \quad \frac{S}{S+3} = \frac{-1}{2} = B$$

$$a=3 \\ b=1$$

#16 rule

$$\frac{1}{1-3} (1e^{-t} - 3e^{-3t}) \\ = \frac{1}{2} (e^{-t} - 3e^{-3t})$$

$$e^{At} = \begin{bmatrix} \frac{1}{2}e^{-3t} + \frac{3}{2}e^{-t} & \frac{1}{2}e^{-3t} + \frac{1}{2}e^{-t} \\ \frac{3}{2}e^{-3t} + \frac{3}{2}e^{-t} & \frac{3}{2}e^{-3t} - \frac{1}{2}e^{-t} \end{bmatrix}$$

Q2 a) check state cont. + obser. of system.

procedure: - find $C = [B \ AB]$
cont.
- $\det C \neq 0 \rightarrow$ then good.

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}_{2 \times 2} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}_{2 \times 1} \quad AB = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$C = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} \therefore \det C = 0 - 1 = -1 \neq 0 \therefore \checkmark$$

procedure: - find $O = \begin{bmatrix} C \\ CA \end{bmatrix}$
obser.
- $\det(O) \neq 0 \rightarrow$ then good.

$$C = [1 \ 0] \\ CA = [1 \ 0] \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} = [0 \ 1]_{1 \times 2}$$

$$O = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det(O) = 1 - 0 = 1 \neq 0 \therefore \checkmark$$

b) $u = -Kx + lr$, find K and l
@ P.D. = 10%, $T_s = 10\text{sec.}$

$$100 e^{\frac{-\zeta\pi}{\sqrt{1-\zeta^2}}} = 10$$

$$\left(\frac{\pi\zeta}{1-\zeta^2}\right)^2 = [\ln 0.1]^2$$

$$e^2 \cdot \pi^2 \rightarrow 5.3 + 5.3e^2 = 0$$

$$e^2[\pi^2 + 5.3] = 5.3$$

$$e = \sqrt{\frac{5.3}{\pi^2 + 5.3}}$$

$$e = 0.591$$

$$10 = \frac{4}{0.591 \times \omega_n}$$

$$5.91\omega_n = 4$$

$$\omega_n = 0.677$$

$$\omega_n^2 = 0.445$$

$$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$$

$$s^2 + 2(0.591)(0.677)s + 0.445 = 0$$

$$s^2 + 0.8s + 0.445 = 0$$

$$[-(A-BK)^{-1}]$$

$$\det(sI - [A-BK])$$

$$\begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} K_1 & K_2 \end{bmatrix} = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ K_1 & K_2 \end{bmatrix} \\ = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 1 & 2+K_2 \end{bmatrix} = \begin{bmatrix} s & -1 \\ K_1-1 & s+K_2-2 \end{bmatrix}$$

$$\det = s(K_2-2) - (1-K_1)$$

$$= sK_2 - 2s - 1 + K_1$$

$$= s^2 + s(K_2-2) + (K_1-1)$$

Feb. 8th.
Notes.

$$\dot{X} = AX + BU$$

$$Y = CX$$

$$\dot{X} = AX + BKX + lrB \text{ sub } u$$

$$\dot{X} = X(A-BK) + lrB \text{ factor } X$$

$$X[sI - (A-BK)] = Blr ?$$

$$X = [sI - (A-BK)]^{-1} Blr \quad X =$$

$$Y = C[sI - (A-BK)]^{-1} Blr \text{ sub } X \text{ into } Y$$

$$\lim_{s \rightarrow 0} \frac{Y}{lr} = C[-(A-BK)^{-1}] B \text{ unit step input.}$$

$$1 = [C(-A+BK)^{-1}B]lr$$

$$Q = [C(-A+BK)^{-1}B]^{-1}$$

find K ?

$$0.8 = K_2 - 2$$

$$K_2 = 2.8$$

$$0.445 = K_1 - 1$$

$$K_1 = 1.445$$

4)

find L

$$L = [C(-A + BK)^{-1}B]^{-1}$$

$$L = \left[[1 \ 0] \begin{bmatrix} 0 & -1 \\ -1 & -2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} [K_1 \ K_2] \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]^{-1}$$

$$\text{adj } A = \begin{bmatrix} K_2 - 2 & 1 \\ -K_1 + 1 & 0 \end{bmatrix}$$

$$L = \left[[1 \ 0] \begin{bmatrix} 0 & -1 \\ -1 & -2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ K_1 & K_2 \end{bmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} =$$

$$A^{-1} = \frac{\text{adj } A}{\det A}$$

$$L = \left[[1 \ 0] \begin{bmatrix} 0 & -1 \\ K_1 - 1 & K_2 - 2 \end{bmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\det A = 0 - (-K_1 + 1) = K_1 - 1$$

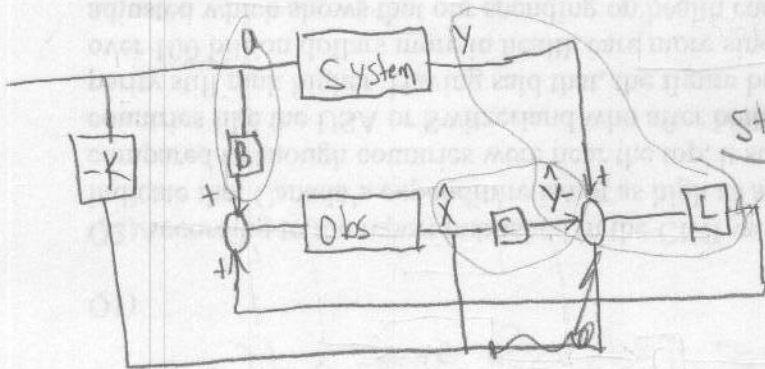
$$L = \left[[1 \ 0] \frac{1}{K_1 - 1} \begin{bmatrix} -2 + K_2 & 1 \\ 1 - K_1 & 0 \end{bmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$L = \left[[1 \ 0] \begin{bmatrix} \frac{K_2 - 2}{K_1 - 1} & \frac{1}{K_1 - 1} \\ \frac{1 - K_1}{K_1 - 1} & 0 \end{bmatrix} \right]^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Sub K_1 in
= 2, 4, ...

$$L = \left[\begin{bmatrix} \frac{K_2 - 2}{K_1 - 1} & \frac{1}{K_1 - 1} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]^{-1} = \left[\frac{1}{K_1 - 1} \right]^{-1}$$

c)



$$u = -KX$$

$$\dot{\hat{x}} = A\hat{x} + Bu + L(y - \hat{y})$$

$$\hat{y} = C\hat{x}$$

State Observer